Instruction Manual

DIGITAL SPEED POTENTIOMETER WITH DISPLAY
FOR AC AND DC DRIVES
Warranty

Dart Controls, Inc. (DCI) warrants its products to be free from defects in material and workmanship. The exclusive remedy for this warranty is DCI factory replacement of any part or parts of such product which shall within 12 months after delivery to the purchaser be returned to DCI factory with all transportation charges prepaid and which DCI determines to its satisfaction to be defective. This warranty shall not extend to defects in assembly by other than DCI or to any article which has been repaired or altered by other than DCI or to any article which DCI determines has been subjected to improper use. DCI assumes no responsibility for the design characteristics of any unit or its operation in any circuit or assembly. This warranty is in lieu of all other warranties, express or implied; all other liabilities or obligations on the part of DCI, including consequential damages, are hereby expressly excluded.

NOTE: Carefully check the control for shipping damage. Report any damage to the carrier immediately. Do not attempt to operate the drive if visible damage is evident to either the circuit or to the electronic components.

All information contained in this manual is intended to be correct, however information and data in this manual are subject to change without notice. DCI makes no warranty of any kind with regard to this information or data. Further, DCI is not responsible for any omissions or errors or consequential damage caused by the user of the product. DCI reserves the right to make manufacturing changes which may not be included in this manual.

WARNING

Improper installation or operation of this control may cause injury to personnel or control failure. The control must be installed in accordance with local, state, and national safety codes. Make certain that the power supply is disconnected before attempting to service or remove any components!!! If the power disconnect point is out of sight, lock it in disconnected position and tag to prevent unexpected application of power. Only a qualified electrician or service personnel should perform any electrical troubleshooting or maintenance. At no time should circuit continuity be checked by shorting terminals with a screwdriver or other metal device.
# Table of Contents

Introduction ............................................................................................................................................. 2  
General Features ..................................................................................................................................... 2  
Models & Options .................................................................................................................................... 3  
  Model Options ....................................................................................................................................... 3  
  Available Options .................................................................................................................................. 3  
Specifications ............................................................................................................................................ 3  
  Electrical ............................................................................................................................................... 3  
  Mechanical ............................................................................................................................................ 3  
  Environmental ....................................................................................................................................... 3  
  Cut-out and Mounting Dimensions ....................................................................................................... 4  
Mechanical Installation ............................................................................................................................ 4  
  Exploded Panel View ............................................................................................................................ 4  
Installation & Diagrams .......................................................................................................................... 5  
  P1 Terminal Block Hook-Up Diagram .................................................................................................... 5  
  P1 Terminal Block Descriptions ........................................................................................................... 5  
  -1 Option Wiring ................................................................................................................................... 6  
Basic Operating Information .................................................................................................................. 6  
  Visual Reference .................................................................................................................................... 6  
  How to Change a Parameter's Value (The Short Story) ........................................................................ 7  
  Operating the User Interface (The Long Story) ...................................................................................... 7  
Detailed Configuration Instructions ......................................................................................................... 8  
  Default Configuration ............................................................................................................................ 8  
  Resetting the Unit to Factory Defaults .................................................................................................. 8  
  JP1 (Program Enable Jumper) ................................................................................................................ 8  
  Software Parameters ............................................................................................................................... 9  
  Parameter Descriptions ........................................................................................................................ 11  
Application Examples .............................................................................................................................. 18  
  User Interface for Industrial Conveyor Oven with AC Drive ................................................................. 18  
  Digital Front Panel for Regenerative Industrial Treadmill ...................................................................... 19  
  Programmable Digital Voltage Source with Enable Switch ............................................................... 21  
Troubleshooting ....................................................................................................................................... 23  
  Technical Support Options .................................................................................................................... 23  
What's Special About www.dartcontrols.com? ......................................................................................... 23
Introduction

The DP4 digital potentiometer is a compact, microprocessor-based unit capable of being either field or factory configured for a number of industry’s user-interface needs. The DP4 allows the user to adjust the displayed value via the front-panel push buttons. As the displayed value is raised or lowered, the output signal from the DP4 follows proportionally according to the unit’s configuration. These units support both unipolar and bipolar output and are capable of automatically inverting, scaling, and offsetting the output as needed. Utilizing Dart’s new modular bus design techniques, the DP4 series is ideal for volume OEM applications requiring specialized inputs and outputs. Contact Dart Controls’ Sales Department for details. This flexibility makes the DP4 series ideal for applications such as:

- Water and Waste Treatment Systems
- Conveyor Oven Controllers
- Synchronized Conveyor Lines

Its durable 1/8 DIN aluminum housings can be easily mounted in a panel or control cabinet. New optional pluggable terminal block allows the installer to quickly install or replace units without the hassle of physically removing and reattaching wires. The units can be ordered with either standard European-style terminal block or optional “pluggable” connector.

General Features

- Microprocessor-based design combines the ultimate in responsiveness and accuracy in one package
- Digital front-end ensures long-term accuracy of output signal over time and temperature
- Non-volatile memory stores adjustable parameters even when power has been removed
- Factory or field programmable via front-panel keypad
- Adjustable parameters include display range, output range, output polarity, alarm options, etc.
- Internal program-enable jumper selectively prevents tampering with unit’s configuration
- Universal power supply accepts line voltages inputs from 85-265VAC @ 50-60Hz without switches or jumpers. The unit automatically adjusts as needed.
- Transient voltage protection prolongs unit’s life in harsh industrial environments
- Self-contained power supply for external sensor, limited to 5V @ 50mA
- Programmable alarm output with Form C contacts rated to 250VAC @ 5A
- 1/8 DIN durable aluminum housing for panel mounting.
- Large 4 digit, 1/2” LED display
- G.E. Lexan membrane and gasket (which are included) meet NEMA 4X standards when used with NEMA 4X enclosures
- European terminal block or pluggable terminal block available
- Wide operating ambient temperature range of -10C to 45C (14F to 113F)
- Multiple operating modes including:
  - Rate Mode – Displays in rate and non-rate units such as RPM, Gallons per Second, & percent
  - Time Mode – Displays in time units such as HH:MM, MM:SS, SS:TT, or other unit
Models & Options

**Model Options**

<table>
<thead>
<tr>
<th>Model</th>
<th>Input Voltage @ 50 - 60Hz</th>
<th>Output Voltage</th>
<th>Pickup or Encoder Required?</th>
</tr>
</thead>
<tbody>
<tr>
<td>DP4</td>
<td>85-265VAC</td>
<td>0-2 VDC THROUGH 0-24 VDC</td>
<td>No</td>
</tr>
</tbody>
</table>

**Available Options**

<table>
<thead>
<tr>
<th>Option Suffix</th>
<th>Description</th>
<th>Example</th>
</tr>
</thead>
<tbody>
<tr>
<td>-1</td>
<td>Expansion board which adds support for remote push button wiring via a European-style terminal block.</td>
<td>DP4-1</td>
</tr>
<tr>
<td>-P</td>
<td>Optional pluggable European-style terminal block</td>
<td>DP4-P</td>
</tr>
<tr>
<td>-9</td>
<td>Blank Lexan</td>
<td>DP4-9</td>
</tr>
</tbody>
</table>

**Specifications**

**Electrical**

- Line Input Voltage: Any Voltage from 85-265 VAC
- Line Input Frequency: Any Freq. from 48-62 Hertz
- Display Range: 0.001 – 9999
- Units of Operation: User Programmable, any Unit
- Onboard Power Supply (Externally Accessible): 5V @ 50mA
- Isolated Alarm Relay Output Ratings: 250VAC @ 5A
- Pot Lo/Hi supply VDC range: 0-2 VDC through 0-24 VDC
- Pot wiper VDC range: Pot Lo +50mV through Pot Hi -50mV

**Mechanical**

- Display Type: LED, Red, 4 Digit, ½” Height
- Housing Type (with supplied gasket in NEMA 4X panel): 1/8 DIN NEMA 4X
- Connector Style (pluggable connector optional): 12-position 5mm European Style
- Terminal Block Torque Setting: 4.4 in. lb. Max or .5Nm
- Faceplate Material: Polycarbonate with GE Lexan Overlay
- Housing Material: Aluminum
- Length (Required Panel Depth): 4.625", 117.48mm
- Faceplate Width: 4.539", 115.29mm
- Weight ASP10: 0.900 lb, 14.4 oz, 408.22g

**Environmental**

- Operating Temperature Range: -10°C to 45°C (14°F to 113°F)
- Operating Humidity Range: 95%, non-condensing
Mechanical Installation

Exploded Panel View

Customer Mounting Panel
(Hole cut-out for control housing approximately 3.622" wide by 1.770" high)

Panel Mounting Gasket
(With the adhesive side of gasket facing the customer mounting panel)

Supplied with each control:
1) Gasket
2) (2) 6-32 x 3/4 panhead black oxide stainless screws
3) (2) #6 nut with lockwasher

Cut-out and Mounting Dimensions

DP4 Control

Housing depth 4.625"
Panel cut-out

.140" x 2

4.000"

3.622"

0.885"

1.770"

2.289"

1.656"

4.625"

5.000"
**P1 Terminal Block Hook-Up Diagram**

**P1 Terminal Block Descriptions**

P1-1 (AC / N) – For single phase AC lines connect the Neutral side of your AC line to this terminal. For systems with two hot AC lines, connect either of the Hot AC lines to this terminal.

P1-2 (AC / L) – For single phase AC lines connect the Hot side of your AC line to this terminal. For systems with two hot AC lines, connect either of the Hot AC lines to this terminal.

P1-3 (HI) - This is the POT HI reference terminal. This terminal must be connected to the most positive speed pot input terminal of the partner control. This terminal will generally be referred to as Pot HI or +V for positive supplies and Com for negative supplies.

P1-4 (WP) - This is the Wiper output terminal. This terminal will output an analog voltage signal proportional to the referenced voltage signals connected to P1-3 (HI) and P1-5 (LO). This terminal should be connected to the wiper or signal input of the partner control.

P1-5 (LO) - This is the POT LO reference terminal. This terminal must be connected to the most negative speed pot input terminal of the partner control. This terminal will generally be referred to as Pot LO or Com for positive supplies and –V for negative supplies.

P1-6 (COM) – This is the common point for the control logic. Any other equipment or source needing to reference the control common will be connected to this terminal.

P1-7 (+5V) – This is a self-contained +5VDC power supply capable of up to 50mA. Various low-voltage sensors can be driven from this supply if desired.

P1-8 (S1) – This is the programmable signal 1 input. It can be configured to perform a number of special features including inhibit and jog.

P1-9 (S2) – This is the programmable signal 2 input. It can be configured to perform a number of special features including inhibit and jog.

P1-10 (1NO) – This is the normally-open contact of the user assignable relay output.

P1-11 (1C) – This is the common contact of the user assignable relay.

P1-12 (1NC) – This is the normally-closed contact of the user assignable relay output.

* P1-8 & P1-9 signal inputs may be programmed for a number of functions.
-1 Option Wiring

The -1 option board is a module which allows external up and down push buttons to be wired to the unit. These buttons operate exactly like the Up and Down buttons on the user interface. This module is commonly used to allow PLCs or hand-held pendants to operate the front-panel remotely. Wires for the external buttons are attached via a 3mm European terminal block on the -1 option board. The buttons are activated by shorting the terminal labeled Com to either the Up or Down terminal.

Basic Operating Information

The DP4 digital potentiometer is a panel-mount digital-to-analog user interface. Put simply, it allows the user to adjust the displayed value via push buttons on the front panel; and, outputs a proportional signal according to its configuration. It can be configured to work with both single and bidirectional partner drives. It also supports both unipolar and bipolar output supplies.

The DP4 can display values in rate and time formats. In Rate mode, output units such as Gallons-per-Minutes, RPM, and Percent are possible with just a few minor adjustments. In Time mode, output units such as Hours:Minutes (HH:MM), Minutes:Seconds (MM:SS), and Seconds:Ticks (SS:TT) are supported. In Time modes, the output will be inversely proportional to the displayed value in order to represent a programmable process time.

See the application examples in this manual for additional information on how the DP4 can be configured.

Visual Reference

See the application examples in this manual for additional information on how the DP4 can be configured.
How to Change a Parameter's Value (The Short Story)
1. Hold down the Enter button until Parameter-Selection Mode is entered
2. Using the Up and Down buttons, select the desired parameter number to view or edit
3. Press the Enter button to change the value of the parameter
4. Using the Up and Down buttons, change the parameter's value as desired
5. Press the Enter button to permanently save the changes (Return to Parameter-Selection Mode)
6. Select parameter zero and press the Enter button to return to Running Mode

Operating the User Interface (The Long Story)
Although the DP4 user interface is very versatile, it is also simple to setup and operate. With just a few button presses, it allows the user to configure a number of adjustable parameters. The LED display has three basic operating modes: Running Mode, Parameter-Selection Mode, and Value Mode. Each of the three modes have specific visual indicators that allow the user to immediately determine the current state or mode of the user interface. Parameter-Selection Mode and Value Mode can only be entered if the Program Enable jumper is in the “On” position.

Running Mode is the default display of the unit when power is applied. The DP4 will spend the majority of its time in this mode. In Running Mode, the display shows the target value in the appropriate user-defined format of rate, time, or percentage. The control will continuously attempt to drive the motor at the requested target rate. In this display mode, the Up and Down buttons increase or decrease the displayed target value until either the display minimum or display maximum limit is reached. Depending on the alarm configuration, these buttons may also serve as an alarm-silence or alarm-reset button. Example displays for rate, time, and follower operating modes are 13.60, 45:30, and 9301.

Parameter-Selection Mode can be entered by simply pressing and holding the Enter button down for three seconds. Once in Parameter-Selection Mode, the far left of the display will be a ‘P’. The right side of the display will indicate the currently selected parameter number for editing purposes. Pressing the Up or Down button will increase or decrease the selected parameter number on the display. Although the parameter numbers are in numerical order, some numbers are skipped. These numbers represent reserved parameters that are not yet implemented and are not displayed. Once the desired parameter number is displayed, a press of the Enter button will change the display to the Value Mode. When in Parameter-Selection Mode, pressing the Enter button with parameter 0 selected will cause the unit to return to Running Mode. Example displays for Parameter-Selection Mode are P 1, P 12, and P 54. See the Software Parameters for a list of available parameters.

Value Mode is used to modify the value of the selected parameter. When in Value Mode, the two dots which form the colon, between digits two and three, will alternately flash (one, then the other) to inform the user that a parameter's value is being edited. Pressing the Up or Down button increases or decreases the selected parameter's value. See the Software Parameters for a list of allowable values and ranges. Value changes take effect immediately. For example, when scrolling through the alarm output conditions, the relay will activate as the always-active selection is passed. Once the desired value is showing in the display window, pressing the Enter button again will return to Parameter-Selection Mode. The new value is not saved in permanent memory until the Enter button is pressed. Removing power from the unit while in Value Mode may result in the specified new value being lost.
Detailed Configuration Instructions

Default Configuration

When shipped from the factory, the following basic settings are in place:

Rate Mode Operation in % Units
Unipolar Output without Deadband
Decimal Point Display: XXX.X
Display Range: 0 - 100.0
Output Range: 0 - 100% of Applied Pot High Voltage
Signal Input 1 (S1) Mode: Force Output to 0% when Low
Signal Input 2 (S2) Mode: Force Output to 0% when Low
Alarm Output: Disabled

Resetting the Unit to Factory Defaults

The factory-default settings can be easily restored using either of two methods. Both methods require the Program Enable jumper to be in the “On” position. The first is to apply power to the unit with both the Enter and Down buttons pressed for 3 seconds. The second is to change the value of parameter 95 to 5.

JP1 (Program Enable Jumper)

The JP1 jumper is located under the dust cover on the back end of the upper board. When the jumper is set to the "Off" position, all programming features are locked out to the front panel user. When the jumper is in the "On" position, the programming parameters are open to change. JP1 is shipped from the factory set in the "On" position.
<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
<th>Value Range (units)</th>
<th>Factory Default</th>
<th>User Settings</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Selecting this item exits to Running Mode</td>
<td>n/a</td>
<td>n/a</td>
<td>n/a</td>
</tr>
<tr>
<td>1</td>
<td>Model Number</td>
<td>40 – DP4 Unit</td>
<td>40</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>Software Build</td>
<td>1 – 9999</td>
<td>n/a</td>
<td>n/a</td>
</tr>
<tr>
<td>3</td>
<td>Hardware Version</td>
<td>1 – 9999</td>
<td>n/a</td>
<td>n/a</td>
</tr>
<tr>
<td>4</td>
<td>Serial Number – Major (reserved)</td>
<td>n/a</td>
<td>n/a</td>
<td>n/a</td>
</tr>
<tr>
<td>5</td>
<td>Serial Number – Minor (reserved)</td>
<td>n/a</td>
<td>n/a</td>
<td>n/a</td>
</tr>
</tbody>
</table>

**Read-Only Parameters**

**General Setup**

10 | Operating Mode | Rate Modes:  
1 – Unipolar Output  
2 – Unipolar Output with Deadband  
3 – Bipolar Output  
4 – Bipolar Output with Deadband  
Time Modes:  
5 – Unipolar Output  
6 – Unipolar Output with Deadband  
7 – Bipolar Output  
8 – Bipolar Output with Deadband  
Other Modes:  
9 – Absolute Value Output with Relay Direction Control  
10 – Absolute Value Output with Relay Direct, Control and Deadband |
| 11 | Display Intensity | 0 – 31 (Dim – Bright) | 26 | |
| 12 | Display Zero Blanking | 1 – ___X Show at least 1 Digit  
2 – ___XX Show at least 2 Digits  
3 – ___XXX Show at least 3 Digits  
4 – ______ Show all 4 Digits | 2 | |
| 13 | Decimal Point Position | 0 – DP Disabled (XXXX)  
1 – X.XXX  
2 – XX.XX  
3 – XXX.X  
4 – XXXX. | 3 | |
| 15 | Keypad Mode | 1 – Linear, Constant Rate  
2 – Non-linear, Accelerating Rate | 2 | |
| 16 | Keypad Scroll Delay | 0 – 30 (Fast – Slow) | 10 | |
| 18 | Power-up Mode | 1 – Default to Zero Display  
2 – Default to Power-up Value  
3 – Default to Previous Running Val. | 3 | |
| 19 | Power-up Value | 0 – 9999 (Display Units) | 0 | |

**Display & Output Setup**

20 | Display Value at Minimum Output | -9999 – 9999 (Display Units) | 0 | |
21 | Display Value at Maximum Output | -9999 – 9999 (Display Units) | 1000 | |
22 | Display Value at Center Output (Bipolar Only) | -9999 – 9999 (Display Units) | 0 | |
25 | Output % - Minimum | 0 – 1000 (1/10th Percent Units) | 0 | |
26 | Output % - Maximum | 0 – 1000 (1/10th Percent Units) | 1000 | |
27 | Output % - Center (Bipolar Modes Only) | 0 – 1000 (1/10th Percent Units) | 500 | |
28 | Output Deadband Width | 0 – 1000 (1/10th Percent Units) | 0 | |
<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
<th>Value Range (units)</th>
<th>Factory Default</th>
<th>User Settings</th>
</tr>
</thead>
</table>
| 30        | S1 Input Configuration | 1 – Output 0% When S1 Low  
2 – Output 0% When S1 High  
3 – Output Setpoint When S1 Low  
4 – Output Setpoint When S1 High  
5 – Output 100% When S1 Low  
6 – Output 100% When S1 High  
7 – Lock Set Point when S1 is Low  
(See: Parameter Description for details) | 1 | |
| 31        | S1 Setpoint | -9999 – 9999 (Display Units) | 0 | |
| 35        | S2 Input Configuration | 1 – Output 0% When S2 Low  
2 – Output 0% When S2 High  
3 – Output Setpoint When S2 Low  
4 – Output Setpoint When S2 High  
5 – Output 100% When S2 Low  
6 – Output 100% When S2 High  
7 – Lock Set Point when S2 is High  
(See: Parameter Description for details) | 1 | |
| 36        | S2 Setpoint | -9999 – 9999 (Display Units) | 0 | |
| 40        | Activation Conditions | 0 – Always Off  
1 – Always On  
2 – Active when Above upper limit  
3 – Active when Below lower limit  
4 – Active inside Range  
5 – Active outside Range  
6 – Active Zero or Equivalent Output  
7 – Relay Direction Control Mode | 0 | |
| 41        | Output Style & Reset Mode | 1 – Constant & Auto Reset  
2 – Constant & Manual Reset  
3 – Pulsed & Auto Reset  
4 – Pulsed & Manual Reset | 1 | |
| 42        | Reset Configuration | 1 – No Sil., Reset on Key  
2 – No Sil., Reset on S2 High  
3 – No Sil., Reset on S2 Low  
4 – Sil., Reset on Key  
5 – Sil., Reset on S2 High  
6 – Sil., Reset on S2 Low | 1 | |
| 43        | Display Flash On Active Alarm | 0 – Alarm Flash Disabled  
1 – Alarm Flash Enabled | 0 | |
| 44        | Pulse on Time | 1 – 3600 (seconds) | 1 | |
| 45        | Pulse off Time | 1 – 3600 (seconds) | 1 | |
| 46        | Pulse Count | 0 – 9999 (pulses) | 0 | |
| 47        | Lower Limit | 0 – 9999 (display units) | 0 | |
| 48        | Upper Limit | 0 – 9999 (display units) | 9999 | |
| 95        | Restore Settings to Factory Default | 0 – Do Nothing & Exit  
5 – Restore Factory Defaults | 0 | |
| 98        | Save to User Default Area | 0 – Do Nothing & Exit  
1 – Save Setting | 0 | |
| 99        | Restore from User Default Area | 0 – Do Nothing & Exit  
1 – Restore Settings | 0 |
Parameter Descriptions

Parameter 0 – Exit to Running Mode
When parameter 0 is selected in Parameter-Selection Mode, the unit will return to Running Mode and display the running value. This should be selected once the changes to the parameters are completed.

Parameter 1 – Model Number (Read Only)
This is a number which represents the base model number for the product. The model code for the DP4 is 40.

Parameter 2 – Software Build (Read Only)
The software build is a code which identifies the software version of the unit.

Parameter 3 – Hardware Version (Read Only)
The hardware version is a code which identifies which hardware was used to build the unit.

Parameter 4 & 5 – Serial Number, Major & Minor (Read Only)
These parameters are reserved for future use as an electronic serial number and are unique to each manufactured unit.

Parameter 10 – Operating Mode
This parameter defines the operating mode for the entire unit. There are two basic modes of operation, Rate and Time. In Rate modes, the unit displays in rate and non-time-based units such as RPM, Gallons per Hour, and Percent of Maximum Output. In Time modes, the unit displays in time-based units using the format AA:BB. The AA:BB format can be adjusted to represent Hours:Minutes or Minutes:Seconds.

Mode 1 – Rate Mode, Unipolar Output
Mode 2 – Rate Mode, Unipolar Output with Deadband
Mode 3 – Rate Mode, Bipolar Output
Mode 4 – Rate Mode, Bipolar Output with Deadband
Mode 5 – Time Mode, Unipolar Output
Mode 6 – Time Mode, Unipolar Output with Deadband
Mode 7 – Time Mode, Bipolar Output
Mode 8 – Time Mode, Bipolar Output with Deadband
Mode 9 – Other Mode, Absolute Value Output with Relay Direction Control
This mode allows the DP4 to interface with bi-directional Controls that have FWD and REV command inputs and use the absolute value of the pot to determine speed only. In this mode, the user must configure the following parameter:
- Display Min, Max, and Center
- Output Min and Max
- Output Deadband (Mode 10 Only!)

Mode 10 – Other Mode, Absolute Value Output with Relay Direction Control and with Deadband Function
Same as Mode 9, except deadband is supported. Must set Deadband value at Item 28.

Parameter 11 – Display Intensity
This parameter adjusts the intensity of the LED display digits in the front panel of the unit. The values of 0 – 31 correspond to a gradual change from very dim to very bright. This is often useful when the DP4 is used in the same panel as other pieces of equipment with LED display and a uniform display brightness is desired. Simply adjust the DP4 to match its surroundings.

Parameter 12 – Display Zero Blanking
This selects the number of display digits that are required to be displayed regardless of the display value. For example, with a Display Zero Blanking setting of 3 and a displayed value of 6, the display would show "_006".

Mode 1: __X Always show at least 1 digit
Mode 2: ___XXAlways show at least 2 digits
Mode 3: ___XXX Always show at least 3 digits
Mode 4: ______XXX Always show all 4 digits

11
Parameter 13 – Decimal Point (DP) Position

This selects the format of the display with respect to the decimal point’s position. This parameter does not affect the value entry for other parameters. The decimal point is only displayed in Rate modes. For example, if the user desires to display numbers such as 12.34 or 1.05, then parameter 13 should be set to 2.

- Mode 0: Fixed XXXX (DP disabled)
- Mode 1: Fixed X.XXX
- Mode 2: Fixed XX.XX
- Mode 3: Fixed XXX.X
- Mode 4: Fixed XXXX.

Parameter 15 – Keypad Mode

This parameter selects the operating mode of the front-panel push buttons. In some applications, increasing or decreasing the scroll rate provides the user more controllability when entering settings. Parameters 14 and 15 affect only the Up and Down buttons when the user interface is in Running Mode. These settings also apply to remote Up / Down buttons which are attached via the -1 option board.

- Mode 1: Linear, Constant Rate
  In linear mode, pressing and holding the Up or Down buttons will cause the display to continuously change value in the requested direction until either the Display Minimum or Display Maximum is reached. The displayed value will scroll at a constant rate which is specified using parameter 16.

- Mode 2: Non-linear, Accelerating Rate
  In non-linear mode, pressing and holding the Up or Down buttons will cause the display to continuously change value in the requested direction until either the Display Minimum or Display Maximum is reached. The displayed value will initially scroll at a slow rate and increase in speed until the maximum scroll rate is achieved. The initial scroll rate is specified using parameter 16.

Parameter 16 – Keypad Scroll Mode

This parameter sets the scroll speed for the front-panel push buttons. The function of this parameter varies slightly depending on the Keypad Mode. See parameter 15 for more details.

Parameter 18 – Power-Up Mode

This parameter defines the mode which determines the default Running Value when power is initially applied to the DP4.

- Mode 1: Default to Zero
  When in this mode, the unit will default to zero (display units).

- Mode 2: Default to Power-Up Value
  When in this mode, the unit will default to the Power-up Value, parameter 19.

- Mode 3: Default to Previously Running Value
  When in this mode, the unit will default to the previous running value before power was removed.
  
  A previous running value must have been active for at least 3 seconds to be recalled after power has been disconnected and reapplied.

Parameter 19 – Power-Up Value

When Power-up Mode is set to 2, this parameter will designate the default display value at power-up in display units.

Parameter 20 – Display Value at Minimum Output

This parameter defines the lower end of the display range. This is the value which limits how low the user is able to scroll the displayed value in Running Mode. In Rate and Time modes, this value is set in display units. This parameter is set without consideration for the decimal point’s position. For example, setting this parameter to 125 would set the lower display limit at 12.5, 0.125, or 125 seconds according to the other configuration parameters.

Parameter 21 – Display Value at Maximum Output

This parameter defines the upper end of the display range. This is the value which limits how high the user is able to scroll the displayed value in Running Mode. In Rate and Time modes, this value is set in display units. This parameter is set without consideration for the decimal point’s position. For example, setting this parameter to 1000 would set the upper display limit at 100.0, 1.000, or 1000 seconds according to the other configuration parameters.
Parameter 22 – Display Value at Center Output
This defines the center value for the display in bipolar (or bidirectional) modes of operation. In bipolar applications, this value should be set to the display value that corresponds to a null or zero output. When in Running Mode, display values above this will produce an output toward the programmed Maximum Output %; whereas, display values below this will produce an output toward the programmed Minimum Output %. As the display value approaches the number programmed in this parameter, the DP4 will produce an output that approaches the percentage programmed in parameter 28. See parameters 25 - 27 and the application examples for additional information.

Parameter 25 – Minimum Output % (in 1/10 percent units)
This parameter sets the output percentage which corresponds to the minimum display value, parameter 20. This parameter has a range of 0 to 1000 which represents 0.0 to +100.0 percent of output. When the user is adjusting the display value towards the programmed minimum display, the output will linearly approach the value of this parameter. For example, setting this parameter to 25 will configure the DP4 to output 2.5% when the user adjusts the display value to equal the display minimum, parameter 20. Setting this minimum percentage higher than the maximum (parameter 26) will cause the polarity of the output to be inverted. See parameters 20 - 22 and the application examples for additional information.

Parameter 26 – Maximum Output % (in 1/10 percent units)
This parameter sets the output percentage which corresponds to the maximum display value, parameter 21. This parameter has a range of 0 to 1000 which represents 0.0 to +100.0 percent of output. When the user is adjusting the display value towards the programmed maximum display, the output will linearly approach the value of this parameter. For example, setting this parameter to 850 will configure the DP4 to output 85.0% when the user adjusts the display value to equal the display maximum, parameter 21. Setting this maximum percentage lower than the minimum (parameter 25) will cause the polarity of the output to be inverted. See parameters 20 - 22 and the application examples for additional information.

Parameter 27 – Center Output % (in 1/10 percent units)
This defines the center percentage for the output in bipolar (or bidirectional) modes of operation. In bipolar applications, this value should be set to the percentage of output that corresponds to a null or zero output of the partner drive. When in Running Mode, display values above the display center (parameter 22) will produce an output toward the programmed Maximum Output %; whereas, display values below the display center (parameter 22) will produce an output toward the programmed Minimum Output %. As the display value approaches the programmed display center value (parameter 22), the DP4 will produce an output that approaches the percentage programmed in this parameter. See parameters 20 - 22 and the application examples for additional information.

Parameter 28 – Output Deadband % (in 1/10 percent units)
This defines the width of the output's deadband. This is the range of output percentage values which will produce a zero or center output percentage in unipolar and bipolar modes respectively. This value is the width of the range in percentage units. For example: If the DP4 were configured for bipolar operation and this parameter were set to 50, then any output which was within 5% of the center output percentage would be forced to the center output value. See parameters 20 - 22 and the application examples for additional information.

Parameter 30 – Signal Input 1 (S1) Configuration
This parameter determines the operating mode of signal input 1 (S1).

Mode 1: Output 0% When S1 Low
When the S1 input is at an electrically low state or wired to the unit's common, the DP4 will force its output to 0%. Once the S1 input returns to an electrically high (+5V) state or allowed to float disconnected, the output will once again correspond to the display value.

Mode 2: Output 0% When S1 High
When the S1 input is at an electrically high (+5V) state or allowed to float disconnected, the DP4 will force its output to 0%. Once the S1 input returns to an electrically low state or wired to the unit's common, the output will once again correspond to the display value.
**Mode 3: Output Setpoint When S1 Low**

When the S1 input is at an electrically low state or wired to the unit's common, the DP4 will force its output to a percentage which corresponds to the programmed jog setpoint, parameter 31. Once the S1 input returns to an electrically high (+5V) state or allowed to float disconnected, the output will once again correspond to the display value.

**Mode 4: Output Setpoint When S1 High**

When the S1 input is at an electrically high (+5V) state or allowed to float disconnected, the DP4 will force its output to a percentage which corresponds to the programmed jog setpoint, parameter 31. Once the S1 input returns to an electrically low state or wired to the unit's common, the output will once again correspond to the display value.

**Mode 5: Output 100% When S1 Low**

When the S1 input is at an electrically low state or wired to the unit's common, the DP4 will force its output to 100%. Once the S1 input returns to an electrically high (+5V) state or allowed to float disconnected, the output will once again correspond to the display value.

**Mode 6: Output 100% When S1 High**

When the S1 input is at an electrically high (+5V) state or allowed to float disconnected, the DP4 will force its output to 100%. Once the S1 input returns to an electrically low state or wired to the unit's common, the output will once again correspond to the display value.

**Mode 7: Lock Set Point when S1 is Low**

“LOC” is displayed when one of the front panel buttons is pressed with S1 in an electrically Low State. Program by bringing S1 terminal P1-8 to electrically High state or allow S1 to float when disconnected from Common terminal P1-6. Enter Program Mode, Select Parameter 30, Press Enter, select value item 7, Press Enter again.

Note: (Select a value 1-6 to Exit the LOCK Set Point than press enter) Select Parameter 0 and press enter to Exit Program Mode. Activate for the new changes to take effect by cycling AC power Off/On.

**Parameter 31 – Signal Input 1 (S1) Setpoint**

When the S1 configuration, parameter 30, is set to one of the setpoint (jog) modes (modes 3 or 4), this parameter defines the jog setpoint in display units. This parameter is always set in display units.

**Parameter 35 – Signal Input 2 (S2) Configuration**

This parameter determines the operating mode of signal input 2 (S2).

**Mode 1: Output 0% When S2 Low**

When the S2 input is at an electrically low state or wired to the unit's common, the DP4 will force its output to 0%. Once the S2 input returns to an electrically high (+5V) state or allowed to float disconnected, the output will once again correspond to the display value.

**Mode 2: Output 0% When S2 High**

When the S2 input is at an electrically high (+5V) state or allowed to float disconnected, the DP4 will force its output to 0%. Once the S2 input returns to an electrically low state or wired to the unit's common, the output will once again correspond to the display value.

**Mode 3: Output Setpoint When S2 Low**

When the S2 input is at an electrically low state or wired to the unit's common, the DP4 will force its output to a percentage which corresponds to the programmed jog setpoint, parameter 36. Once the S2 input returns to an electrically high (+5V) state or allowed to float disconnected, the output will once again correspond to the display value.

**Mode 4: Output Setpoint When S2 High**

When the S2 input is at an electrically high (+5V) state or allowed to float disconnected, the DP4 will force its output to a percentage which corresponds to the programmed jog setpoint, parameter 36. Once the S2 input returns to an electrically low state or wired to the unit's common, the output will once again correspond to the display value.

**Mode 5: Output 100% When S2 Low**

When the S2 input is at an electrically low state or wired to the unit's common, the DP4 will force its output to 100%. Once the S2 input returns to an electrically high (+5V) state or allowed to float disconnected, the output will once again correspond to the display value.
Mode 6: Output 100% When S2 High
When the S2 input is at an electrically high (+5V) state or allowed to float disconnected, the DP4 will force its output to 100%. Once the S2 input returns to an electrically low state or wired to the unit's common, the output will once again correspond to the display value.

Mode 7: Lock Set Point when S2 is High
"LOC" is displayed when one of the front panel buttons is pressed with S2 in an electrically High State. Program by bringing S2 terminal P1-9 to electrically Low state or wire to unit's Common terminal P1-6. Enter Program Mode, Select Parameter 35, Press Enter, select value item 7, Press Enter again.

Note: (Select a value 1-6 to Exit the LOCK Set Point than press enter) Select Parameter 0 and press enter to Exit Program Mode. Activate for the new changes to take effect by cycling AC power Off/On.

Parameter 36 – Signal Input 2 (S2) Setpoint
When the S2 configuration, parameter 35, is set to one of the setpoint (jog) modes(modes 3 or 4), this parameter defines the jog setpoint in display units. This parameter is always set in display units.

Parameter 40 – Alarm 1 Conditions
This defines which conditions will result in the alarm 1 output being activated.

Mode 0: Always Inactive
The alarm output will remain in an inactive state. In this state, the NC and C contacts will be internally electrically connected.

Mode 1: Always Active (When Power Is Applied)
The alarm output will become active when the power is applied to the unit. In this state, the NO and C contacts will be internally electrically connected.

Mode 2: Active When Display Value Above Limit
The alarm output will activate when the displayed value is above the upper limit setting, parameter 48.

Mode 3: Active When Display Value Below Limit
The alarm output will activate when the displayed value is below the lower limit setting, parameter 47.

Mode 4: Active When Display Value Inside Range
The alarm output will activate when the displayed value is greater than or equal to lower limit settings and less than or equal to the upper limit setting.

Mode 5: Active When Display Value Outside Range
The alarm output will activate when the displayed value is less than the lower limit setting or greater than upper limit setting.

Mode 6: Active When Display Value Results in a Zero or Equivalent Output
If the display is set to a value that produces a zero output or is within the programmed deadband, then the alarm is activated.

Mode 7: Relay Direction Control Mode
In this mode, the relay output will determine which direction is being requested. This will typically be used with Item 10 modes 9 & 10.
Forward = relay not energized; Reverse = relay energized

Parameter 41 – Alarm 1 Output Style & Reset Configuration
This setting configures the output mode and reset method for the alarm output.

Mode 1: Constant & Auto Reset
In this mode, the alarm output will remain active until the alarm condition ceases to exist. The alarm will automatically reset when the conditions return to normal.

Mode 2: Constant & Manual Reset
In this mode, the alarm output will remain active until the alarm is reset manually. See parameter 42 for details.
Mode 3: Pulse & Auto Reset
In this mode, the alarm output will pulse on and off until the alarm condition ceases to exist. The pulsed modes are commonly used for audible alarms where a constant output would be considered distracting or awkward. The alarm will automatically reset when the conditions return to normal.

Mode 4: Pulse & Manual Reset
In this mode, the alarm output will pulse on and off until the alarm is reset manually. See parameter 42 for reset details. The pulsed modes are commonly used for audible alarms where a constant output would be considered distracting or awkward.

Parameter 42 – Alarm 1 Reset Configuration
This setting determines which actions will cause an active alarm to be silenced or reset.

Mode 1: No Silencing, Reset On Any Button Press
In this mode, an active alarm cannot be silenced. Once the alarm condition ceases to exist, however, any user-interface button may be pressed to cause a manual reset.

Mode 2: No Silencing, Reset On S2 Input High (Not Wired To Common)
Similar to Mode 1. Once the alarm condition ceases to exist, setting the S2 input to a high (+5V) state or allowing it to float disconnected will cause a manual reset.

Mode 3: No Silencing, Reset On S2 Input Low (Wired To Common)
Similar to Mode 1. Once the alarm condition ceases to exist, setting the S2 input to a low (COM) state or wiring it to common will cause a manual reset.

Mode 4: Silencing Enabled, Reset On Any Button Press
When the conditions for an active alarm persist, pressing any user-interface button will result in the alarm being silenced or deactivated, but not reset. A second attempt to reset the alarm must be made after the condition cease to exist to clear the alarm.

Mode 5: Silencing Enabled, Reset On S2 Input High (Not Wired To Common)
Similar to Mode 4. Setting the S2 input to a high (+5V) state or allowing it to float disconnected will cause the alarm to be silenced or reset depending on the current state of the alarm conditions.

Mode 6: Silencing Enabled, Reset On S2 Input Low (Wired To Common)
Similar to Mode 4. Setting the S2 input to a low (COM) state or wiring it to common will cause the alarm to be silenced or reset depending on the current state of the alarm conditions.

Parameter 43 – Alarm 1 Display Flash On Alarm
This will cause the display to flash when an alarm condition is active.

Parameter 44 – Alarm 1 Pulse on Time
This parameter defines the number of seconds the output should be enabled during the ‘on’ phase of an active pulsing alarm’s output.

Parameter 45 – Alarm 1 Pulse off Time
This parameter defines the number of seconds the output should be disabled during the ‘off’ phase of an active pulsing alarm’s output.

Parameter 46 – Alarm 1 Pulse Count
This setting determines how many pulses are output when the alarm is activated and is configured in pulse output style. When 0 is entered, the unit will be set for continuous pulses while the alarm is active.

Parameter 47 – Alarm 1 Lower Limit
This setting defines either the lower limit or lower end of a range for the alarm region. Alarm limits are set in display units without regard to decimal point or colon position. In Rate Modes, a limit of 123 could represent a display value of 123, 12.3, 1.23, or 0.123. When in Time Mode, a limit of 123 would represent 1:23 on the display.
Parameter 48 – Alarm 1 Upper Limit
This setting defines either the upper limit or upper end of a range for the alarm region. Alarm limits are set in display units without regard to decimal point or colon position. In Rate Mode, a limit of 123 could represent a display value of 123, 12.3, 1.23, or 0.123. When in Time Mode, a limit of 123 would represent 1:23 on the display.

Parameter 95 – Factory Default Command
When set to a value of 5, the unit will be reset to factory default settings. This can also be achieved by applying power to the unit with both the Enter and Down buttons depressed. The programming jumper must be in the "On" position for this method to function.

Parameter 98 – Save to User Default Area Command
When set to a value of 1, the unit will store all adjustable parameters to the user default area. The user default area is intended to be a location where an OEM or integrator can store settings specific to their application. Using this, an OEM can easily refresh their custom settings in the field if an end-user accidentally reconfigures the unit unsuccessfully. Another common use for this area is testing and initial setup. The user can store known-good settings here and easily experiment without the fear of losing the optimal configuration.

Parameter 99 – Restore from User Default Area Command
When set to a value of 1, the unit will restore all adjustable parameters from the user default area. See parameter 98 for additional information.
Application Examples

User Interface for Industrial Conveyor Oven with AC Drive

Description:
An industrial tunnel oven currently uses an AC inverter drive with an attached speedpot to control the motor which drives its train. Because the process time for the oven is known, it is preferred that the user be able to set the process time in minutes and seconds on a digital display. Using a DP4, this is quite simple and requires a minimum amount of installation and training effort to complete. In this example, a DP4 has been connected to the existing AC inverter drive and a remote speed select switch which allows the user to select from one of two preprogrammed time settings (2 or 4 minutes) or to enter a manual mode where the display of the unit can be directly adjusted using the front panel's up and down arrow buttons. The desired display range is from 90 seconds (1:30) to 600 seconds (10:00). Calibration and measurement from the previously installed speed potentiometer has shown that a voltage output of 30% - 76% of the applied reference voltage from the AC inverter will produce the desired time range.

Application Diagram:
Digital Front Panel for Regenerative Industrial Treadmill

Description:
A bidirectional industrial treadmill with a speed range of +/- 12 mph is currently powered by an analog regenerative control using an external speedpot to adjust the speed. Unfortunately, the speed pot does not offer enough accuracy and repeatability to allow for proper operation of the treadmill. A DP4 has been added to the system to give it a quick and easy to use digital front panel. The DP4 has also been wired to support an external jog switch for rapidly (and temporarily) setting the belt speed to a predetermined value of 5 mph. An enable switch allows the user to immediately force the regen to a stopped conditional should it be necessary. For safety reasons, the unit will default to zero output when power is initially applied.
Application Diagram:

Wiring Diagram:

* Size fuse according to unit and application. See electrical specifications for maximums.
Programmable Digital Voltage Source with Enable Switch

Description:
A test stand needs an easily adjustable and accurate 0 - 5VDC signal to test the response of a device under test. The digital display of the voltage source (DP4) should read in 1/100ths of a volt (V.VV). When the unit initially has power applied, it should always default to an output voltage of zero volts. When the output is greater than 0 volts, an illuminated alarm should light and flash to indicate that the device under test is being actuated.

Application Diagram:
Wiring Diagram:

Parameter Configuration:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>12</td>
<td>3</td>
<td>Zero-blanking set to 3 digits</td>
</tr>
<tr>
<td>13</td>
<td>2</td>
<td>Decimal point position set to XX.XX on display</td>
</tr>
<tr>
<td>18</td>
<td>1</td>
<td>Power-up display value set to default at 0.00</td>
</tr>
<tr>
<td>20</td>
<td>0</td>
<td>Display minimum set to 0.00</td>
</tr>
<tr>
<td>21</td>
<td>500</td>
<td>Display maximum set to 5.00</td>
</tr>
<tr>
<td>25</td>
<td>0</td>
<td>Set output minimum to 0% (0V)</td>
</tr>
<tr>
<td>26</td>
<td>1000</td>
<td>Set output maximum to 100% (5V)</td>
</tr>
<tr>
<td>40</td>
<td>2</td>
<td>Alarm output active when above upper limit</td>
</tr>
<tr>
<td>41</td>
<td>3</td>
<td>Alarm output set to pulse and auto-reset</td>
</tr>
<tr>
<td>48</td>
<td>0</td>
<td>Alarm upper limit set to activate above value of 0</td>
</tr>
</tbody>
</table>

* Size fuse according to unit and application. See electrical specifications for maximums.
# Troubleshooting

<table>
<thead>
<tr>
<th>Problem</th>
<th>Possible Case</th>
<th>Solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>Display is blank</td>
<td>Power not applied</td>
<td>Using a volt meter, verify that a voltage between 85 and 265VAC is measured between the L and N terminal block positions.</td>
</tr>
<tr>
<td></td>
<td>Defective unit</td>
<td>Contact technical support for additional help and instructions.</td>
</tr>
<tr>
<td>Display is dim</td>
<td>Display intensity parameter is too low</td>
<td>Editing and increasing the display intensity parameter should cause the display digits to become brighter.</td>
</tr>
<tr>
<td>When power is applied, “LF-L” is displayed</td>
<td>AC line supplying power to unit has too much noise</td>
<td>Review routing of power wires in machine to minimize electrical noise. Look for other devices which share the same circuit which may be producing unacceptable levels of line noise. In some applications, such as welding equipment, a careful regiment of applying an AC line filter, re-route wires, dividing circuits, using shielded cable, and properly grounding devices will usually solve the problem. The unit is designed to operate with AC lines from 48-62 Hertz (cycles per second). This is typically not a problem because the international standards are 50 and 60 Hertz.</td>
</tr>
<tr>
<td></td>
<td>AC line supplying power to unit has an abnormally low frequency</td>
<td></td>
</tr>
<tr>
<td>When power is applied, “LF-H” is displayed</td>
<td>AC line supplying power to unit has too much noise</td>
<td>Review routing of power wires in machine to minimize electrical noise. Look for other devices which share the same circuit which may be producing unacceptable levels of line noise. In some applications, such as welding equipment, a careful regiment of applying an AC line filter, re-route wires, dividing circuits, using shielded cable, and properly grounding devices will usually solve the problem. The unit is designed to operate with AC lines from 48-62 Hertz (cycles per second). This is typically not a problem because the international standards are 50 and 60 Hertz.</td>
</tr>
<tr>
<td></td>
<td>AC line supplying power to unit has an abnormally high frequency</td>
<td></td>
</tr>
<tr>
<td>The alarm output does not seem to function</td>
<td>Alarm output parameters not configured properly</td>
<td>Alarm output parameters not configured properly Review alarm output parameters. The alarm relay output can be tested by selecting the “Always On” value for the Activation Condition parameters for the alarm output. When doing this, the relay click should be audible and the NC (Normally Closed) and C (Common) terminals should become internally shorted at the terminal block.</td>
</tr>
</tbody>
</table>

## Technical Support Options

- Visit the Dart Controls Web Site at: www.dartcontrols.com
- Email technical support at: sales@dartcontrols.com
- Telephone technical support at 317-733-2133 ext. 460

## What's Special About www.dartcontrols.com?

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  NEMA 4 Enclosed

- Stock # 2M510
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  Open Chassis SCR

- Stock # 6Z386A
  1/50 - 2 Hp
  NEMA 4/4X
  Extra Features

- Stock # 6Z385A
  1/50 Hp - 2.0 Hp
  NEMA 4/4X
  Extra Features

- Stock # 5JJ62
  Variable AC Voltage control

- Stock # 1XC92A
  Field Programmable
  Closed-loop DC Speed Control

- Stock # 3VU57
  Field Programmable
  Digital Tachometer and Rate Meter

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  Reversing Switch; Cover Kits

- NEMA 4X Low Voltage
  PWM DC Drive
  12-48DVC in / out; 10A

- C-Face Mount Speed Sensor
  1, 2, 15 or 60 pulse output

- Advanced Digital DC Drives
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